

For Iron and Steel Industry



**ABSOCODER CONVERTER** 

NCV-220HSSIL8

**Specifications & Instruction Manual** 

 $\epsilon$ 

Applicable sensor: VLS-8SM

#### GENERAL SAFETY RULES

(Please read this safety guide carefully before operation)

Thank you very much for purchasing our product.

Before operating this product, be sure to carefully read this manual so that you may fully understand the product, safety instructions and precautions.

- Please submit this manual to the operators actually involved in operation.
- Please keep this manual in a handy place.

Signal Words

Safety precautions in this guide are classified into DANGER and CAUTION.

Symbol	Meaning	
DANGER	Incorrect handling may cause a hazardous situation that will result in death or serious injury.	
CAUTION	Incorrect handling may cause a hazardous situation that will result in moderate injury or physical damage.	

Instructions accompanied by a symbol ACAUTION may also result in serious damage or injury. Be sure to follow the all instructions accompanied by the symbol.

#### **Graphic Symbols**

Symbol	Meaning
$\bigcirc$	Indicates prohibited items.
0	Indicates items that must be performed to.

#### **Application Limitation**

This product is not designed to be used under any situation affecting human life. When you are considering to use this product for special purposes such as medical equipment, aerospace equipment, nuclear power control systems, traffic systems, and etc., please consult with NSD.

This product is designed to be used under the industrial environments categorized

The supplier and user may be required to take appropriate measures.

#### 1. Handling Precautions

# DANGER



Do not touch components inside of the controller; otherwise, it will cause electric shock.



Do not damage the cable by applying excessive load, placing heavy objects on it, or clamping; otherwise, it will cause electric shock or fire.



Turn the power supply OFF before wiring, transporting, and inspecting the controller; otherwise, it may cause electric shock.



Provide an external safety circuit so that the entire system functions safely even when the controller is faulty.



Connect the grounding terminal of the controller; otherwise, it may case electric shock or malfunction

#### **CAUTION**



- Do not use the controller in the following places; water splashes. the atmosphere of the corrosion, the atmosphere of the flammable vapor, and the side of the combustibility. Doing so may result in fire or the controller may become faulty.



- Be sure to use the controller and the ABSOCODER sensor in the environment designated by the general specifications in the manual. Failure to do so may result in electric shock, fire, malfunction or unit failure.
- Be sure to use the specified combination of the ABSOCODER sensor, controller and sensor cable; otherwise, it may cause fire or controller malfunction.

#### 2. Storage

## **CAUTION**



Do not store the controller in a place exposed to water, or toxic



Be sure to store the controller in designed temperature and humidity range, and do not exposed to direct sunlight. Be sure to consult with NSD when the controller is stored for long

periods.

#### 3. Transport

# **CAUTION**



Do not hold the cable or shaft of ABSOCODER sensor during transport; otherwise, it will cause injury or controller malfunction.

#### 4. Installation

# **CAUTION**



- Do not step on the ABSOCODER sensor or place heavy objects on the controller; otherwise, it will cause injury.
- Do not block the exhaust port or allow any foreign matter to enter the controller; otherwise, it will cause fire or unit failure.



- Be sure to secure the controller and ABSOCODER sensor with the provided brackets; otherwise, it may cause malfunction, injury, or
- Be sure to secure the specified distance between the main body and the control panel or other equipments; otherwise, it may cause malfunction.

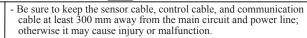
#### 5. Wiring

# DANGER



- Be sure to secure the terminal block firmly; otherwise, it may have risk of fire.
- Be sure to mount the terminal cover provided with the controller, before supplying the power, starting operation after the installation, and wiring; otherwise, it may cause electric shock.

# **CAUTION**





- Be sure to connect all cables correctly; otherwise, it may cause injury or controller malfunction.
- Be sure to firmly connect the external I/O connectors and sensor connectors; otherwise, it may cause incorrect inputs and outputs or

#### 6. Operation

# **CAUTION**

- Do not change the controller's function switch settings during the



- operation; otherwise, it will cause injury.

  Do not approach the machine after instantaneous power failure has been recovered.
- Doing so may result in injury if the machine starts abruptly, it will cause injury.
- Be sure to check that the power supply specifications are correct; otherwise, it may caused controller failure.
- Be sure to provide an external emergency stop circuit so that operation can be stopped with power supply terminated immediately.
- Be sure to conduct independent trial runs for the controller before mounting the controller to the machine;
- otherwise, it may cause injury. When an error occur, be sure to eliminate the cause, ensure safety, and reset the error before restarting operation; otherwise, it may cause injury.

#### 7. Maintenance And Inspection

# **CAUTION**



Do not disassemble, remodel, or repair the unit; otherwise, it will cause electric shock, fire, and unit malfunction



The capacitor of the power line deteriorates through prolonged use. We recommended that the capacitor be replaced every five years to prevent secondary damage.

#### 8. Disposal





Be sure to handle the controller as industrial waste while disposing of it.

# REVISION HISTORY

The Document No. appears at the upper right of this manual's cover page.

		upper right of this manual's cover page.
Document No.	Date	Revision Description
ZEF005350800	4, Jun., 2013	1st Edition
		Japanese document: ZEF005350700
ZEF005350801	14, Mar., 2016	2nd Edition
		Japanese document: ZEF005350701
ZEF005350802	17, Jan., 2017	3rd Edition
		Japanese document: ZEF005350702
ZEF005350803	25, Dec., 2020	4th Edition
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#### 1. OVERVIEW

NCV-220HSSI is the ABSOCODER converter which is compatible with SSI (Synchronized Serial Interface).

This converter can detect the machine position by combining the ABSOCODER sensor.

The host controller can read this position data in SSI signals.

#### 1-1. Features

#### Superior durability

NSD's original ABSOCODER is used as the position sensor which features a no-contact construction for excellent durability. This sensor offers problem-free operation, even in environments where it is exposed to vibration, impact shocks, extreme temperatures, oil, and dust.

#### Compact design

The unit's outside dimensions (39(W) x 155(H) x 93(D)) were miniaturized. DIN rail can be used, so mounting is much easier.

#### Less wiring

The wiring can reduce by using the SSI communication.

#### Two axes ABSOCODER sensor can connect

The machine positions for two axes can be detected by one converter. The space-saving in the control panel can be conducted.

## Rotating direction setting function

The increase direction of the position data can be set by changing the setting switch.

#### Output code switch function

The converter can switch codes (gray / binary) by changing the setting switch.

#### Zero point setting function

The zero point can set in desired machine position by pressing the zero point setting button on the panel or turning the zero point signal ON from external input. The converter has a setting button and input signal for two axes, so the zero point setting is available for each axis.

#### Error detection function

An error status can be checked by the monitor LED of the converter when an error occurs. The PLC and host controller can also check the error, because the converter has a system ready signal.

#### Compliance with CE standards

The converter complies with CE (EMC Directive) standards.

# 1-2. Limitations

# / Important

Cautions concerning power-off and error occurrence

If the sensor moves while the converter power is OFF or when an error is present, it mightn't detect accurate machine positions thereafter.

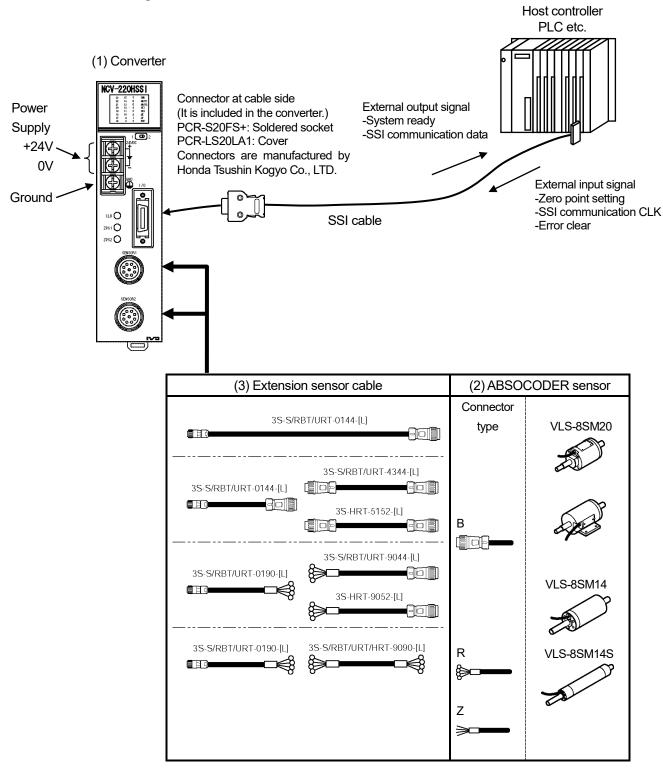
The zero position setting should be done after turning ON the power supply or clearing the error.

## 2. MODEL SELECTION WHEN ORDERING

The following figure indicates the connection configuration of NCV-220HSSI.

Before ordering, refer to the connection configuration and model list. Please prepare by customer except 1 to 3 in the connection configuration.

#### Connection configuration



## Model List

# **♦** Converter

No.	Model	Description	
(1)	NCV-220HSSIL8	For linear type ABSOCODER sensor	

## **♦** ABSOCODER sensor

No.	Item	Model		Description
	VLS-8SM20-[1]FA[2][L]	Flange-mount type	[1]: Stroke VLS-8SM20: 50, 100, 150, 200, 250, 300, 350 VLS-8SM14(S):	
(2)	Linear type	VLS-8SM20-[1]LA[2][L]	Base-mount type	[2]: Connector type  B: Standard connector
(2) ABSOCODER sensor	VLS-8SM14-[1]FB[2][L]	Flange-mount type	(NJW-2012PM8, manufacturer: Nanaboshi Electric Mfg.Co,Ltd.) Contact your NSD representative for VLS-8SM14 and VLS-8SM14S. R: Crimping terminals (R1.25-4)	
		VLS-8SM14S-[1]FB[2][L]	Flange-mount type	Z: No connector  [L]: Interconnecting sensor cable length (m): 2, 5,10, 20

## **♦** Extension sensor cable

No.	Model	Description
(3)	3S-[1]-[2] [3]-[L]	[1]···Cable type S: Standard cable RBT: Robotic cable URT: Semi-heat-resistant robotic cable HRT: Heat-resistant robotic cable  [2]···Connector (Converter side) 01: Connector for connecting to a converter (R04-PB9M8.0A) 43: Standard connector (NJW-2012-PM8) 51: Standard connector (NJW-2012-PM10) 90: Crimping terminals (R-1.25-4)  [3]···Connector (Sensor side) 44: Standard connector (NJW-2012-AdF8) 52: Standard connector (NJW-2012-AdF10) 90: Crimping terminals (R-1.25-4)  [L]···Cable length (m) Contact your NSD representative for the cable length.

# 3. SPECIFICATIONS

# 3-1. Converter Specifications

3-1-1. General specification

Items	Specifications		
Power supply voltage	24VDC±10% (including ripple)		
Power consumption	10W or less		
Insulation resistance	20 M-Ohms or more between external DC power terminals and ground		
insulation resistance	(by 500 VDC insulation resistance tester)		
Withstand voltage	500 VAC, 60Hz for 1 minute between external DC power terminals and ground		
Vibration resistance	20m/s <sup>2</sup> 10 to 500Hz, 10cycles of 5 minutes in 3 directions,		
VIDIALION TESISLANCE	conforms to JIS C 0040 standard		
Ambient operating temperature	0 to +55°C (No freezing)		
Ambient operating humidity	20 to 90 %RH (No condensation)		
Ambient operating environment	Free from corrosive gases and excessive dust		
Ambient storage temperature	-25 to +70°C		
Grounding	Must be securely grounded (ground resistance of 100 ohm or less)		
Construction	Book-shelf type within enclosure, DIN rail mountable		
Outside dimension (mm)	39(W) x 155(H) x 93(D) Refer to dimensions for details.		
Mass	Approx. 0.4kg		

3-1-2. Performance specification

Items	Specifications		
	VLS-8SM20		
Applicable sensor	VLS-8SM14		
	VLS-8SM14S		
Resolution	1μm(8.192mm/8192 divisions)		
Total number of divisions	Standard pitch x number of pitches (8192 divisions (213) x max. 2048 pitches)		
Position detection format	Semi-absolute format		
Communication interface	SSI (Synchronized Serial Interface)		
Number of communication	2ch		
channels	ZCII		
Output code	Binary or gray code (switchable)		
Number of detection axes	2		
Position data sampling time	0.2ms		
Position data increase direction	CW or CCW (switchable)		
Front panel function	Zero point setting, error clear		
Switch	Position data increase direction setting (CW / CCW)		
(on rear face of product)	Output code (binary /gray)		
(orreal lass of product)	Axis-2 error detection (enable / disable)		
Monitor LED	Display of position data, power supply status, sensor disconnected error,		
WOING LED	sensor data error, low power supply error, memory error, converter error		
	Axis-1 zero point setting: 1-point		
Input signal	Axis-2 zero point setting: 1-point		
	Error clear signal: 1-point		
Output signal	Axis-1 system ready signal: 1-point		
Output signal	Axis-2 system ready signal: 1-point		
Applicable standard	CE Marking (EMC directive)		

# 3-1-3. Input / output specification

	Input	Output		
Items	Specifications	Items	Specifications	
Input signals	ZPS1 (axis-1 zero point setting): 1-point ZPS2 (axis-2 zero point setting): 1-point CLR (error clear): 1-point	Output signals	NOR1 (axis-1 system ready signal): 1-point NOR2 (axis-2 system ready signal): 1-point	
Input circuit	DC input, photo-coupler isolation	Output circuit	Photo-coupler isolation	
Input logic	Negative logic	Output logic	Negative logic	
Rated input voltage	24VDC	Rated load voltage	24VDC (30VDC max)	
Input current	10mA TYP (24VDC)	Max. load current	100 mA	
		Max. voltage drop when ON	1.5V (100mA)	
	Circui	t diagram		
Sink connection				
Source connection	R	2, 4, 12 1, 3, 11 14, 15 5, 13	Input circuit  Output circuit	
	R	2, 4, 12 1, 3, 11 14, 15 5, 13	Input circuit  Output circuit	

# 3-1-4. SSI connector pin arrangement

Pin No.	Signal name	Pin No.	Signal name	Connector dimension
1	ZPS2-	11	ZPS1-	
2	ZPS2+	12	ZPS1+	Shows the pin arrangement as viewed from the soldering terminals side.
3	CLR-	13	NOR1-	, and the second
4	CLR+	14	NOR1+	View A
5	NOR2-	15	NOR2+	
6	SG (0V)	16	SG (0V)	910 1 19 18 18 18 18 18 18 18 18 18 18 18 18 18
7	CLK2-	17	DATA2-	910 8 7 19 18 7 6 7 7 16 5 4 7 7 15 15 14 3 2 1 7 7 1 12 12 14 11 12
8	CLK2+	18	DATA2+	3 4 7 4 7 13 12 1 12 1 1 1 1 1 1 1 1 1 1 1 1 1 1
9	CLK1-	19	DATA1-	
10	CLK1+	20	DATA1+	

## Accessary

Connector model: PCR-S20FS+ / PCR-LS20LA1 (Manufacturer: HONDA TSUSHIN KOGYO CO., LTD)

# Usage cable

Use the cable for RS-422 / RS-485 (twist-pair cable with shield).

Sheath diameter:  $Max \phi 10$  or less Wire size: 0.2mm<sup>2</sup> (AWG24)

## Reference

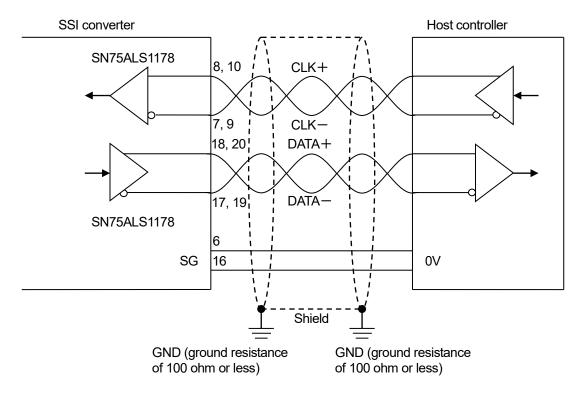
We conduct the operation check with using the following cable.

CO-SPEV-SB (A) 10P x 0.2SQ LF (Manufacturer: Hitachi Cable, Ltd.)

# 3-1-5. SSI communication specification

Items	Specifications					
Interface	SSI (Synchronized Serial Interface)					
Communication format	RS-422 standard					
Numbers of channels	2 channels (per sensor axis)					
Communication signal	DATA+, DATA-, CLK+, CLK-					
Code	Gray / binary					
Data length	25-bit					
Monoflop time	20 μs					
Transmission speed: cable length	1MHz: 20m, 500kHz: 60m, 250kHz: 160m, 125kHz: 320m					

# 3-1-6. SSI communication circuit diagram



## \* Method of shield grounding

The shield of the cable should be grounded (ground resistance of 100 ohm or less) at both sides of SSI converter and host controller.

# 3-2. ABSOCODER Sensor Specifications

# (1) VLS-8SM20

Items			Specifications					
Model			VLS-8SM20					
Max. detection st	roke		350 mm					
Absolute detectio	n ran	ge	8.192 mm					
Resolution			1 μ m(8.192mm/8192)					
Linearity error			Customer's Special Specifications					
Mass		Head	4.5+0.15 x [cable length(m)] kg					
IVIASS		Rod	0.4+0.0025 x [stroke (mm)] kg					
Sliding resistance	)		69 N or less (7kgf or less)					
Permissible mech	nanica	al speed	1000 mm/s					
Ambient tempera	turo	Operating	-10 to +80°C					
Ambient tempera	lure	Storage	-10 to +80°C					
Ambient operating	g hun	nidity	_					
Vibration resistan			2.0 x 10 <sup>2</sup> m/s <sup>2</sup> (20G) 200Hz up/down 4h, forward/back/left/right 2h each,					
Vibration resistan	Ce		conforms to JIS D 1601 standard					
Shock resistance			4.9 x 10 <sup>3</sup> m/s <sup>2</sup> (500G) 0.5ms, up/down x 3 times,					
SHOCK TESISIANCE			conforms to JIS C 5026 standard					
Protection rating			IP67, conforms to JEM 1030 standard					
Frotection rating			IP69K, conforms to ISO 20653 standard					
Interconnecting c	able		2 · 5 · 10 · 20m					
Max. sensor	Star	ndard cable	3S-S 200m					
cable length	Rob	otic cable	3S-RBT 100m					
Surface	Hea	ıd	Electroless nickel plated					
Surface	Rod		Hard chromium electro plated					
Material	Hea	ıd	Steel					
ivialeriai	Rod		Steel					

## (2) VLS-8SM14, VLS-8SM14S

Ite	ms		Specifications					
Model			VLS-8SM14		VLS-8SM14S			
Max. detection st	roke		200 mm					
Absolute detectio	n ran	ge		8.192 r	nm			
Resolution			1 μ m(	(8.192n	nm/8192)			
Linearity error			Customer's	Specia	l Specifications			
Mass		Head	1.1+0.07 x [cable length(m)] k	кg	0.8+0.07 x [cable length(m)] kg			
เทสรร		Rod	0.0012 x ([ı	0.0012 x ([rod length (mm)] kg				
Sliding resistance	)		15 N or le	ess (1.	5kgf or less)			
Permissible mech	nanica	al speed	1	1000 m	m/s			
Ambient tempera	tura	Operating	-10 to +80°C					
Ambient tempera	ture	Storage	-10 to +80°C					
Ambient operating	g hun	nidity						
Vibration resistan	CE		2.0 x 10 <sup>2</sup> m/s <sup>2</sup> (20G) 200Hz up/down 4h, forward/back 2h,					
Vibration resistan	· ·		conforms to JIS D 1601 standard					
Shock resistance			4.9 x 10 <sup>3</sup> m/s <sup>2</sup> (500G) 0.5ms, up/down x 3 times,					
OHOOK TOSIStarioo			conforms to JIS C 5026 standard					
Protection rating			IP67, conform	ns to JE	M1030 standard			
Trotection rating			IP69K, conforms to ISO20653 standard					
Interconnecting c	able		2 •	5 • 10	• 20m			
Max. sensor	Star	ndard cable	3S-S 200m					
cable length	Rob	otic cable	38	S-RBT	100m			
Surface	Hea	nd	Electro	less nic	ckel plated			
Guilace	Rod	<u> </u>	Hard chromium electro plated					
Material	Hea	nd		Stee	el			
iviatorial	Rod	<u> </u>		Stee	.l			

# 3-3. Extension Sensor Cable Specification

Items	Specifications									
Model code	3S-S	3S-RBT	3S-URT	3S-HRT						
Cable type	Standard cable	Robotic cable	Semi-heat-resistant robotic cable	Heat-resistant robotic cable						
Diameter		φ8		φ9.5						
Operating temperature range	-5~	+60°C	0~+150°C							
Insulator	Irradiated cross linked formed polyethylene									
Sheath	Polyvinyl ch	loride mixture	Heat-resistant polyvinyl chloride mixture	Fluoro-rubber						
Construction		7-core, 1 triple with sh	ield + 2 pairs with shield							
Color of sheath	Dark brown	Dark brown Blue								
Advantage	Extensible for long distances	Superior flexibility; id	erior flexibility; ideal for moving place  flexible; imoving moving							

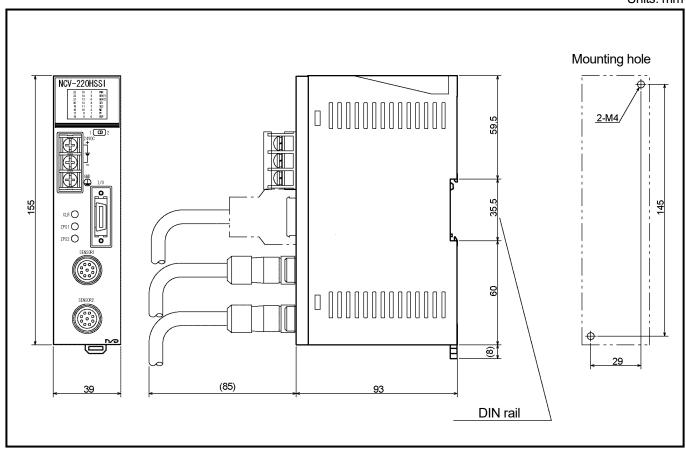
#### [Remark]

Contact your NSD representative when the extension cable combines different types of cables.

# 4. DIMENSIONS

# 4-1. Converter Dimension

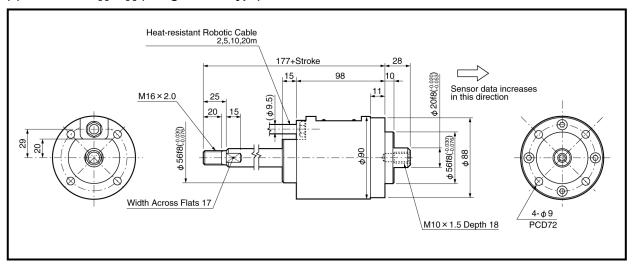
Units: mm



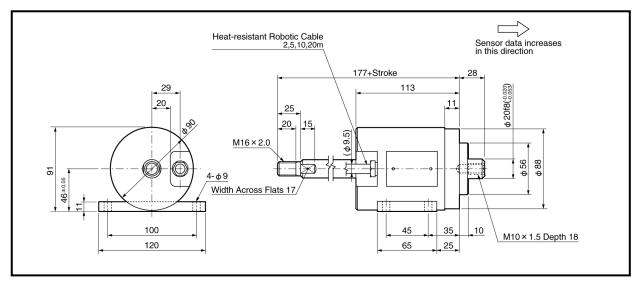
# 4-2. ABSOCODER Sensor Dimensions

# (1) VLS-8SM20-[]FA[] (Flange-mount type)

Units: mm

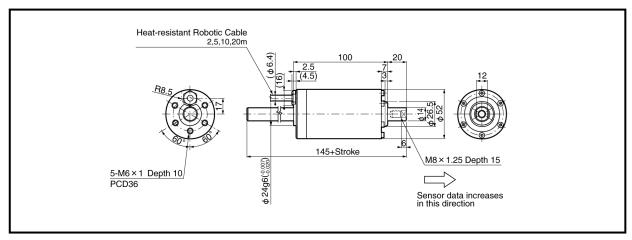


## (2) VLS-8SM20-[]LA[] (Base-mount type)

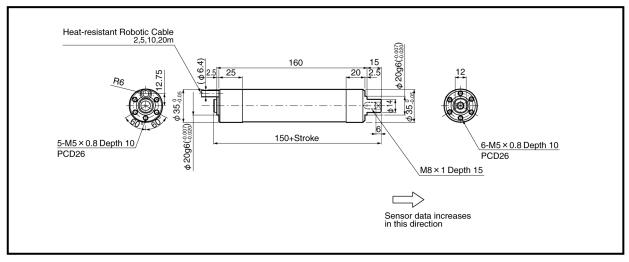


# (3) VLS-8SM14-[]FB[] (Flange-mount type)

## Units: mm



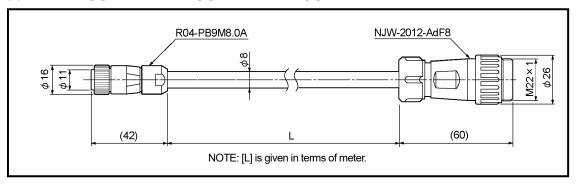
# (4) VLS-8SM14S-[]FB[] (Flange-mount type)



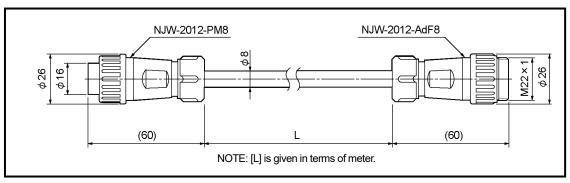
## 4-3. Extension Sensor Cable Dimensions

# (1) 3S-S-0144-[L] / 3S-RBT-0144-[L] / 3S-URT-0144-[L]

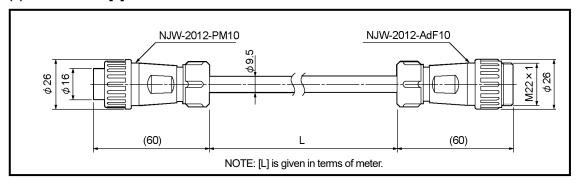
Units: mm



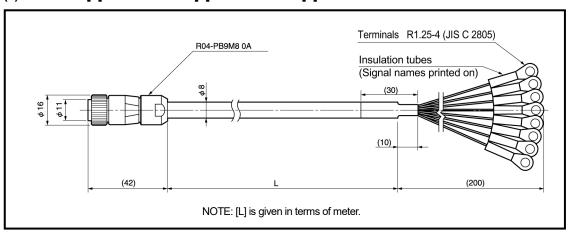
## (2) 3S-S-4344-[L] / 3S-RBT-4344-[L] / 3S-URT-4344-[L]



## (3) 3S-HRT-5152-[L]

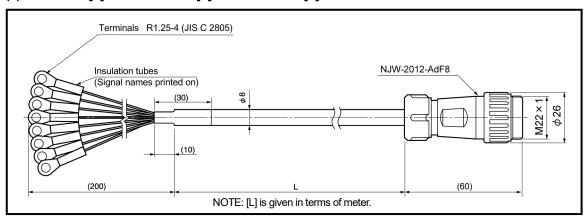


## (4) 3S-S-0190-[L] / 3S-RBT-0190-[L] / 3S-URT-0190-[L]

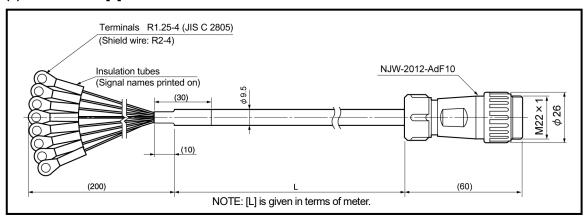


#### (5) 3S-S-9044-[L] / 3S-RBT-9044-[L] / 3S-URT-9044-[L]

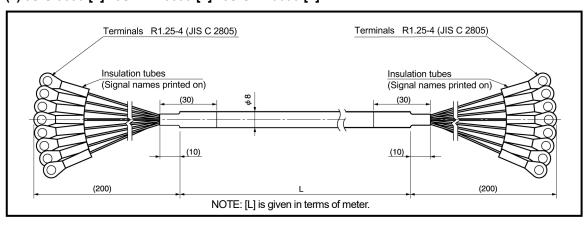
Units: mm



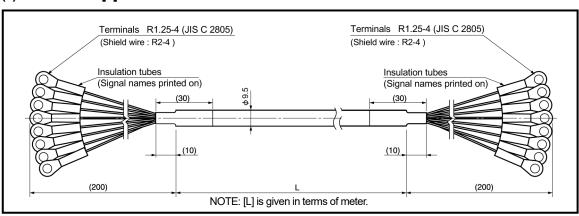
#### (6) 3S-HRT-9052-[L]



#### (7) 3S-S-9090-[L] / 3S-RBT-9090-[L] / 3S-URT-9090-[L]

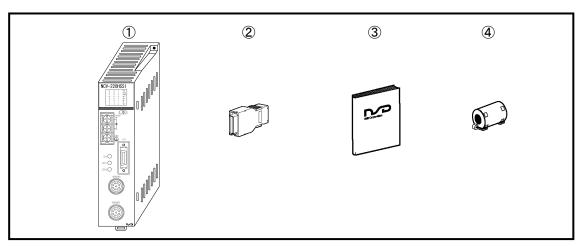


#### (8) 3S-HRT-9090-[L]



# 5. CHECKING THE CONTENTS OF THE SHIPPING CASE

Open the packing case, and verify that all items are present. When extension sensor cables are ordered, they are packed separately.



①Converter······ 1 unit
②SSI connector 1 piece Connector: PCR-S20FS+ Cover: PCR-LS20LA1 Manufactured by Honda Tsushin Kogyo Co., LTD.
③Manual · · · · · 1 piece
4 Clamp filter 1 piece  Model: ZCAT3035-1330  Manufactured by TDK Corporation.

#### 6. INSTALLATION

#### 6-1. Converter Installation Conditions and Precautions

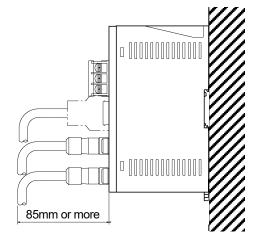
When installing the converter, the following conditions and precautions should be observed.

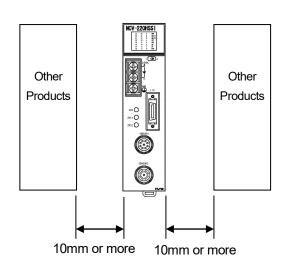
#### -Installation Site

- (1) Avoid sites where the unit is exposed to direct sunlight.
- (2) The ambient temperature should never exceed a 0 to 55°C range.
- (3) The ambient humidity should never exceed a 20 to 90% RH range.
- (4) Do not install the unit in areas where condensation is likely to occur (high humidity with extreme temperature changes).
- (5) Avoid sites where dust is excessive.
- (6) Do not install in areas with an excessive amount of salt and/or metal chips.
- (7) Do not install in areas where flammable and / or corrosive gases are present.
- (8) Avoid areas where splashing water, oil or chemicals are likely to occur.
- (9) Avoid areas where vibration and shocks are excessive.

#### -Installation cautions

- (1) Install inside the control cabinet.
- (2) Install in a vertical direction so that the characters are visible.
- (3) If a DIN rail mounting format is used, insert until the latch mechanism catches with an audible click. Secure between end plates at both sides.
- (4) In high vibration areas, secure tightly with 2 M4 screws.
- (5) Install as far from high voltage lines and power lines as possible in order to minimize noise influences.
- (6) Allow 85mm or more space at the converter's front side for plugging in and unplugging the connector.
- (7) Peripheral components should be arranged so as not to obstruct converter installation, removal, and connector plugging/unplugging.
- (8) Space out 10mm or more betweeen the converter and peripheral components in order not to obstruct the converter's heat dissipation.

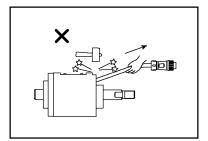




#### 6-2. ABSOCODER Sensor Installation Conditions and Precautions

The installation conditions and precautions for ABSOCODER sensor are described in this section.

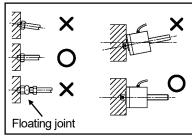
(1) Do not apply excessive forces to the cable port, and avoid damaging the cable.

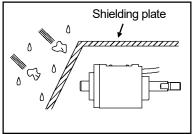


(2) The part of a machine mounted the sensor rod must travel in the same direction as the sensor rod extends and contracts.

Do not use a floating joint.

(3) When the cable port is exposed, a shielding plate should be installed as shown in the right figure.





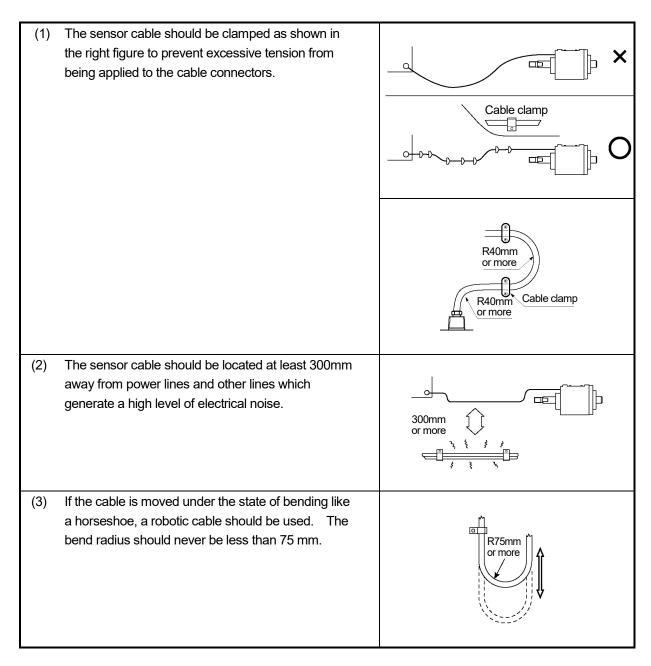
Contact your NSD representative for details of the installation conditions and precautions for ABSOCODER sensor.

## 7. WIRING

## 7-1. Connection between Converter and ABSOCODER Sensor

The length of the extendable cable has a limitation depending on the models of ABSOCODER sensor and sensor cable. For more details refer to "3-2. ABSOCODER Sensor Specifications".

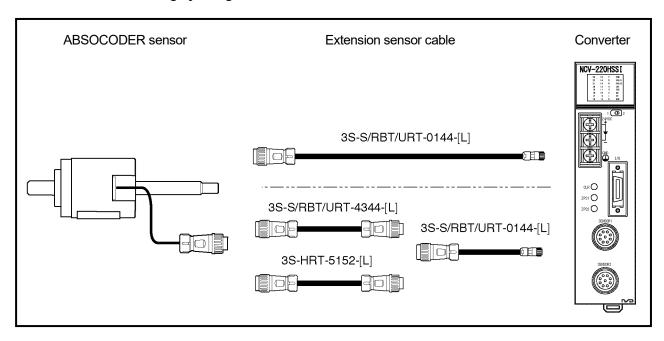
## Wiring precautions



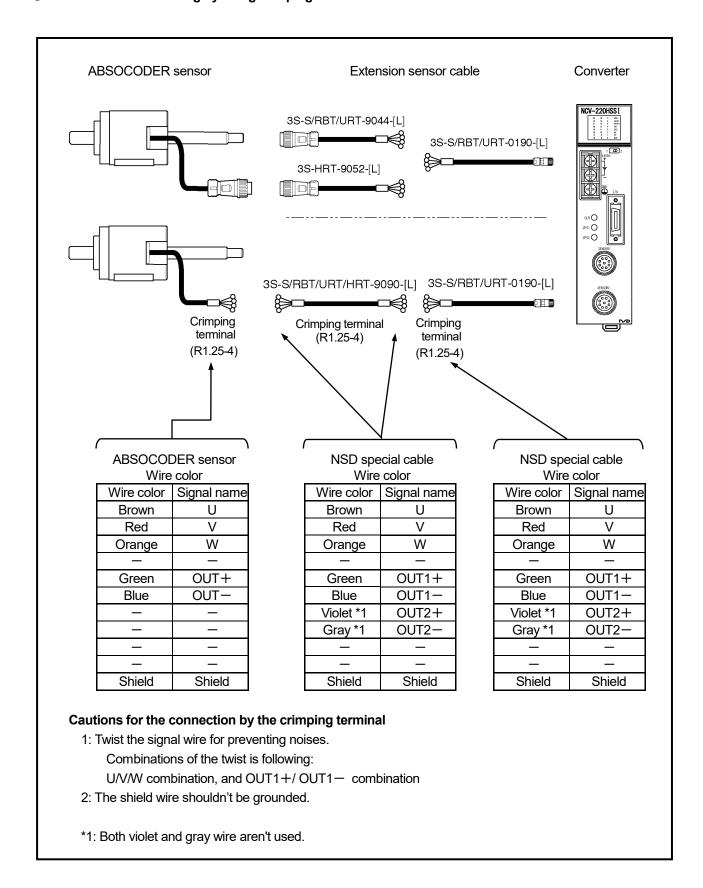
# 7-1-1. Connection configure example of the sensor cable

Indicates the ABSOCODER sensor cable connection example when connecting by the standard connector or the crimping terminal.

## • In the case of connecting by using the standard connector



#### In the case of connecting by using crimping terminals

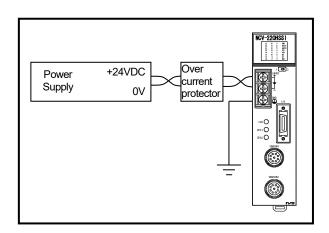


## 7-2. Power Supply Connection

The power supply should be connected as described below:

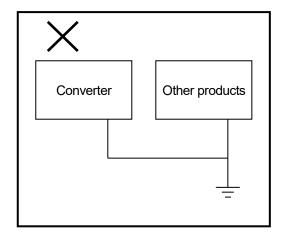
#### Power Supply

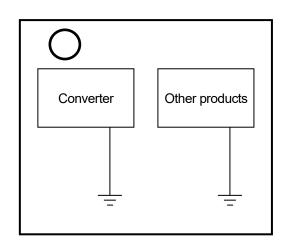
- Choose the power supply capacity which is more than twice the power consumption of the converter.
   The power consumption of the converter is 10W or less.
- -The input power supply should be isolated from the commercial power supply.
- The power cable should be as thick as possible to minimize voltage drops.
- -Twist the power cable for preventing noises.
- -Use the M4 size crimp lug terminals with insulating sleeves in order to prevent short circuit caused by loose screws.
- -The terminal block tightening torque is 1.8 N·m (16 lb·in).



#### Ground

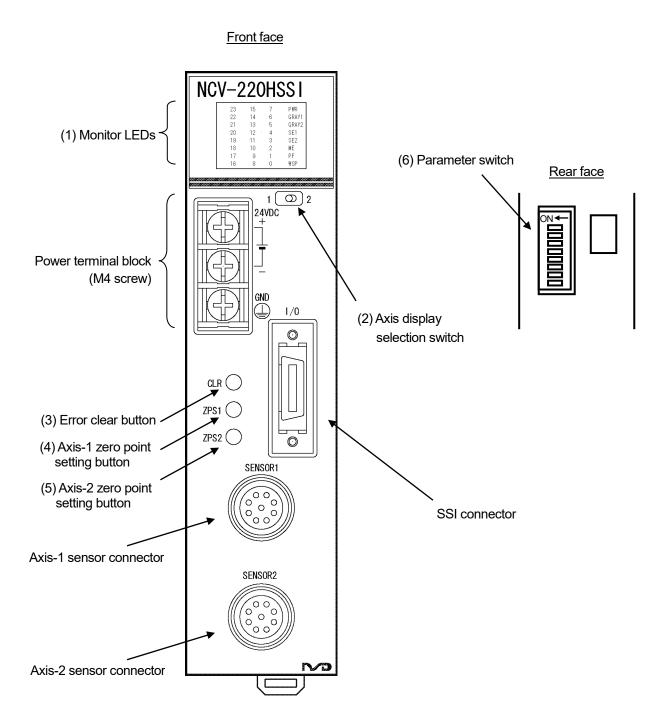
- -The unit should be securely grounded (ground resistance of 100ohm or less) to prevent electrical shocks.
- -The ground wire should be connected to the ground terminal directly.
- -The terminal block tightening torque is 1.8 N·m (16 lb·in).





# 8. NOMENCLATURE

## 8-1. Part Identification



## 8-2. Function and Name of Display and Setting Area

#### (1) Monitor LEDs

Name	Description					
PWR (green)	LED turns ON when the power supply is normal status.					
GRAY1 (green)	LED turns ON when the axis-1 output code is gray.					
GRAY2 (green)	LED turns ON when the axis-2 output code is gray.					
SE1 (red)	LED turns ON when the axis-1 sensor is disconnected.					
SET (Ted)	LED blinks when the axis-1 sensor data error.					
SE2 (red)	LED turns ON when the axis-2 sensor is disconnected.					
SEZ (Ieu)	LED blinks when the axis-2 sensor data error.					
ME (red)	LED turns ON when the memory has an error.					
PF (red)	LED turns ON when the power supply voltage is low.					
WSP (red)	LED blinks or ON when the converter has an error.					
	Indicates a position data in a binary code.					
0 to 22 (=====)	The axis-1 position data is displayed when the axis display selection switch is "1".					
0 to 23 (green)	The axis-2 position data is displayed when the axis display selection switch is "2".					
	Indicates in 0 to 23 (24-bit)					

#### (2) Axis display selection switch

Selects the position data which is displayed on the monitor LED on the panel.

- · The axis-1 current position data is displayed on monitor LED when the switch is "1".
- The axis-2 current position data is displayed on monitor LED when the switch is "2". All LEDs from 0 to 23 blink when the axis-2 is not used.

#### (3) Error clear button [CLR]

The error display turns OFF by pressing this button [CLR] after removing an error cause. The system ready signal of the connector output turns ON.

#### (4) Axis-1 zero point setting button [ZPS1]

Axis-1 position data is set to "0" by pressing this button [ZPS1]. Do this procedure after moving the machine position to the zero point position (0 position).

#### (5) Axis-2 zero point setting button [ZPS2]

Axis-2 position data is set to "0" by pressing this button [ZPS2]. Do this procedure after moving the machine position to the zero point position (0 position).

# (6) Parameter switch (Rear face)

The switch status is set as the parameter when the power supply turns ON.

The operation isn't influenced even though the switch is changed during the operation.

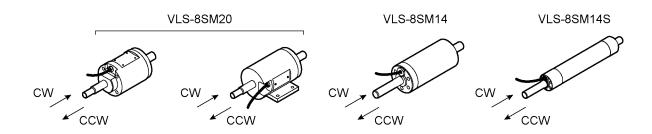
Switch No.	Parameter name	Switch setting	Description	Factory setting
1	Axis-1 position data ON : CCW increase direction OFF: CW		Specify the direction in which the axis-1 position data should increase. *1	OFF
2	Axis-2 position data increase direction	ON : CCW OFF: CW	Specify the direction in which the axis-2 position data should increase. *1	OFF
3	Axis-1 output code	ON : Gray OFF: Binary	Outputs Axis-1 position data in the gray code when the setting is ON.	OFF
4	Axis-2 output code	ON : Gray OFF: Binary	Outputs Axis-2 position data in the gray code when the setting is ON.	OFF
5	Reserved	Fixed at OFF	Keep this switch in the OFF position.  The correct operation cannot be guaranteed if this switch is set to the ON position.	OFF
6	Reserved	Fixed at OFF	Keep this switch in the OFF position.  The correct operation cannot be guaranteed if this switch is set to the ON position.	OFF
7	Reserved	Fixed at OFF	Keep this switch in the OFF position.  The correct operation cannot be guaranteed if this switch is set to the ON position.	OFF
8	Axis-2 (enabled / disabled)	ON : Disable OFF: Enable	When this switch is set to the ON position, error will not occur even if the axis-2 sensor is not connected. Axis-2 position data is "0", and monitor LEDs from 0 to 23 blink.	OFF

<sup>\*1:</sup> The position data increases or decreases according to the ABSOCODER sensor's rod travel direction.

The direction in which the position data increases is specified by a switch on the converter's rear face.

Increase direction	Alteration of the position data
OFF: CW (Factory setting)	Position data  Position  Position  detection range
ON : CCW	Position data  Position  CW direction  detection range

## ◆ Travel direction of the rod



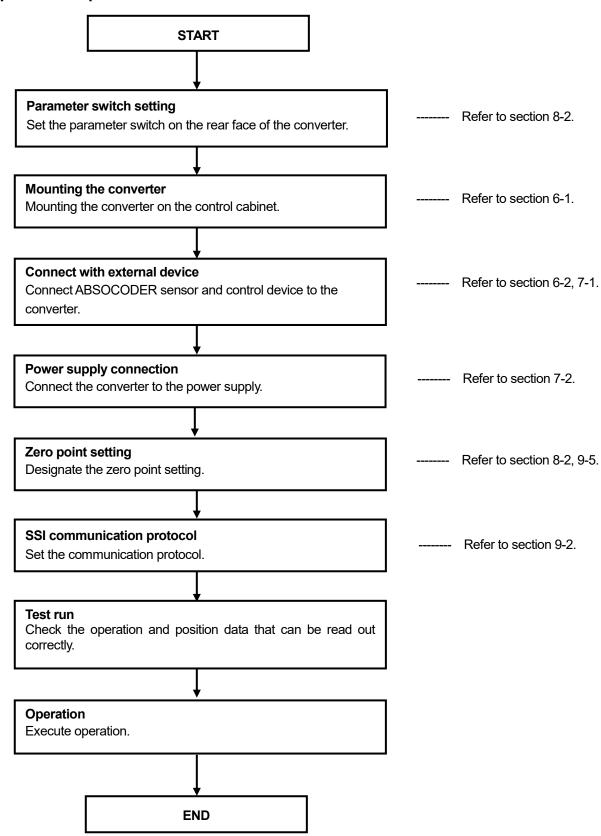
# Important

# Position data "increase direction" setting caution

Do not change the position data "increase direction" switch setting while the power is ON, as this could cause an accident.

## 9. OPERATION

## 9-1. Operation Sequence

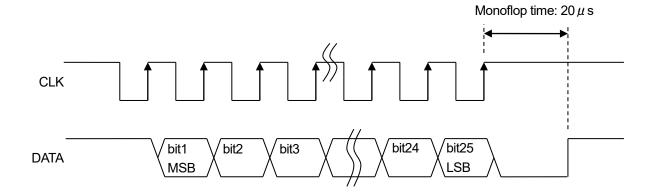


#### 9-2. SSI Communication Protocol

bit	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25
data	0	D	D	D	D	D	D	D	D	D	D	D	D	D	D	D	D	D	D	D	D	D	D	D	D
		23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

- (1) Set the following of the host PLC side.
  - Absolute Sensor \*1 (the data length): 25-bit.
  - Steps/Revolutions \*1: 8192.

# 9-3. SSI Communication Timing Chart



- (1) The newest DATA is latched and MSB is sent to the DATA line when the first CLK rises. After that, the DATA is sent at each clock rising until LSB. The DATA will be "L" after LSB DATA is sent. (monoflop time)
- (2) The same DATA will be sent from MSB again when the CLK is supplied newly within monoflop time.

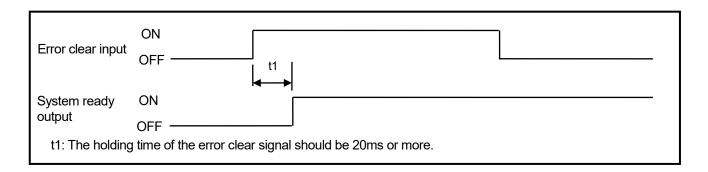
  The DATA becomes "H" when the CLK isn't supplied newly within the monoflop time.

  After time passes more than monoflop time, the newest data will send from MSB again when CLK rises.

<sup>\*1</sup> The items name is written when using SM338 manufactured by SIEMENS AG.

# 9-4. Error Clear Input (CLR)

The chart below indicates the error clear input timing.



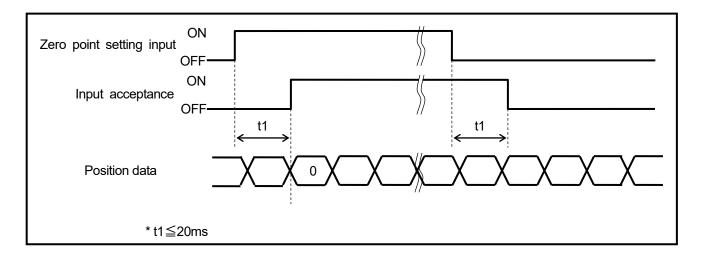
#### **Important**

The error clear input must be ON 20ms or more.

The error clear signal must be turned OFF after clearing the error.

# 9-5. Zero Point Setting Input (ZPS1, ZPS2)

The chart below indicates the zero point setting input timing.



#### **Important**

The zero point setting input must be ON 20ms or more.

The zero point setting signal must be turned OFF after setting the zero point.

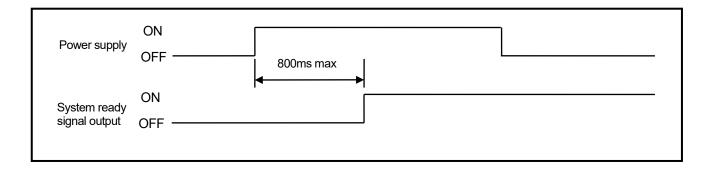
# 9-6. System Ready Signal Output (NOR1, NOR2)

The system ready signal indicates that the normal position data is output from the converter.

The signal is ON when ABSOCODER sensor and converter operate normally.

For your safety, read the position data when the system ready signal is ON.

The following figure indicates the timing from turning ON the power supply to outputting the system ready signal.



# **10. INSPECTION**

The inspection should be conducted once every 6 months to a year.

Any inspected items which do not satisfy the criteria shown below should be repaired

Inspection item	Inspection Description	Criteria	Remark	
Power supply	Measure the voltage fluctuation at the power supply terminal block of the converter to determine if it is within the prescribed range.	Within 21.6V to 26.4VDC range	Tester	
Ambient Conditions	Check the ambient temperature.	ABSOCODER sensor: -10 to +80°C Converter: 0 to +55°C	Thermometer	
Conditions	There should be no accumulation of dust.	None		
	Verify that the sensor is securely mounted.	There should be no looseness.		
	Verify that the sensor rod is securely coupled to the machine.	There should be no looseness.	No. and	
Mount	Check for severed cables.	Cable should appear normal.	Visual	
Conditions	Verify that the sensor cable connector is plugged in all the way.	There should be no looseness.	Inspection	
	Verify that the SSI connector is plugged in all the way.	There should be no looseness.		

## 11. TROUBLESHOOTING

11-1. Display and Countermeasure when an Error Occurred

Error monitor	Name	Probable cause	Error cancel procedures	
"SE 1" or "SE 2"	Sensor disconnected	Sensor connector is disconnected or loose.	After removing an error cause, clear the error by either way: - Press CLR button Turn ON the error clear input signal.	
LED is	error *1	Sensor cable is severed.	Replace the sensor cable.	
ON	5.7.6.	ABSOCODER sensor failure	Replace the ABSOCODER sensor.	
		Converter failure	Replace the converter.	
"SE 1" or "SE 2" LED blinks	Sensor data error *1	Sensor connector is loose.  ABSOCODER sensor was shocked excessively.  Wiring has a noise source	After removing an error cause, clear the error by either way: - Press CLR button Turn ON the error clear input signal.	
		Sensor cable is severed.	Replace the sensor cable.	
"PF" LED is ON	Low power supply error	Voltage drop of the power supply. Instantaneous power failure of the power supply.	After removing an error cause, clear the error by either way: - Press CLR button Turn ON the error clear input signal.	
"ME" LED Is ON	Memory error	Memory data has been changed due to external noise, etc.	After moving the machine to the zero point, press "ZPS1" and "ZPS2" buttons at same time in order to clear an error.  NOTE  The position data is changed to "0" when clearing the error. (The zero point setting is executed.)	
"WSP"	Converter	Watchdog timer error occurs.	Replace the converter.	
LED is ON	error	vvalcindog lifter error occurs.	Neplace the Conventer.	
"WSP" LED blinks	Converter error	Converter failure	Replace the converter.	

<sup>\*1:</sup> The sensor disconnected error would be displayed, if both the sensor disconnected error and sensor data error are occurred at the same time.

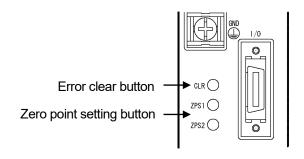
Note

The error wouldn't be cleared if a cause isn't removed.

#### 11-2. Error Clear Method

The error clear is executed by following methods.

- (1) In the case of clearing SE and PE
  - · Press the error clear button [CLR] on the front panel.
  - Turn on the error clear input signal [CLR] in the I/O connector from PLC or host controller.



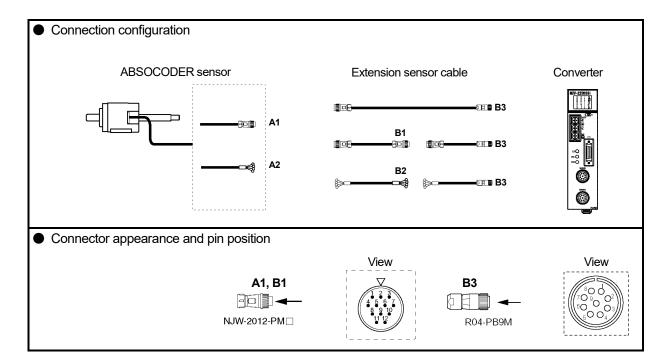
- (2) In the case of clearing ME
  - $\cdot\,$  Press both zero point setting buttons [ZPS1 and ZPS2 ] on the front panel at the same time.

# **- MEMO -**

#### 11-3. ABSOCODER Sensor Check List

 Applicable ABSOCODER sensor models VLS-8SM20 VLS-8SM14

VLS-8SM14S



• Connector pin position and standard coil resistance ranges (at 25°C)

Confidence pur position and standard controlistance ranges (at 25 C)																				
	Check	position			Standard coil resistance [ $\Omega$ ]															
A1, A2,	B1, B2	B3		B3		В3		В3		B3		B3		B3		Signal		VLS-8SM14		
Pin No.	Wiring color	Pin No.	Wiring color	names	VLS-8SM20	VLS-8SM14S														
1	Brown	1	Brown	U																
2	Red	2	Red	V	114 to 154	132 to 152														
3	Orange	3	Orange	W																
4	_	4	_	_	_	_														
5	Green	5	Green	OUT+	162 to 202	150 to 190														
6	Blue	6	Blue	OUT-	162 to 202	150 to 180														
7	_	7	1	ı																
8	_	8	ı	I																
9	_	9	Shield	Shield																
10	_																			
11	Shield																			
12	_	-	-	-																

The above standard coil resistance ranges are referential data to assist wiring disconnection diagnosis and are not product specification values. There may be no wiring disconnection even when the resistance measurement is out of the standard resistance range.

#### Circuit resistance check

#### [Measurement method]

Measure resistance at Point A or B using a circuit tester or other appropriate device.

Have Point A connected to measure at Point B.

If the connector is off, identify the line by the wiring color.

#### [Check details]

Refer to the previous page for the connector pin number.

Check position	Criterion	Check position	Criterion
Between brown and red	The measured value should be in the range of the standard coil resistance. *1	Between brown and green	
Between brown and orange		Between brown and shield	
Between red and orange		Between green and shield	∞
Between green and blue			
		Between frame and each wire or shield	

\*1: If checks are done at Point B, the measurement value is [Standard coil resistance + extension sensor cable resistance].

Extension sensor cable resistance value

The resistance value of the NSD special cable is  $0.2\Omega/m$  (loop resistance).

Consider resistance variations due to temperature, which, relative to the standard temperature (25°C), increases 0.4% when the temperature rises 1°C and decreases 0.4% when the temperature falls 1°C.

#### Insulation check

#### [Measurement method]

Measure using a 500 VDC insulation tester.

#### [Check details]

Refer to the previous page for the connector pin number.

Check position	Criterion
Between brown and green	10MΩ or more
Between brown and shield	
Between green and shield	
Between frame and each wire or shield	

# **⚠** NOTES

- 1. Make sure to disconnect the ABSOCODER sensor from the converter before carrying out insulation checks
- 2. If there is a risk that energization may cause damages to the electronic circuits in and around the machine, remove the ABSOCODER sensor from the machine.
- 3. After completing the checks, short-circuit between the pins to discharge remaining voltage before connecting the ABSOCODER sensor to the converter.

## 12. CE MARKING

This product conforms to the EMC Directive.

#### 12-1. EMC Directives

It is necessary to do CE marking in the customer's responsibility in the state of a final product.

Confirm EMC compliance of the machine and the entire device by customer because EMC changes configuration of the control panel, wiring, and layout.

#### 12-2. EMC Directive and Standards

EMC consists of emission and immunity items.

It conforms to Table (see below) of EMC standards and Testing.

Class	Standard No.	Standard Name
Emission (EMI)	EN61000-6-4	Generic standards. Emission standard for industrial environments
Immunity (EMS)	EN61000-6-2	Generic standards. Immunity standard for industrial environments
	EN61000-4-2	Electrostatic Discharge
	EN61000-4-3	Radiated, Radio frequency, Electromagnetic Field
	EN61000-4-4	Electrical Fast Transient / Burst
	EN61000-4-5	Surge Immunity
	EN61000-4-6	Conducted Disturbances, Induced by Radio-Frequency Fields
	EN61000-4-8	Power Frequency Magnetic Field

# 12-3. Low Voltage Directive

This product doesn't apply to low-voltage directive for the equipment of 24VDC power supply.

#### 12-4. Restrictions

In this section, restrictions are described for conforming to the EMC Directive.

#### SSI cable

Install the cramp filter (accessory ) to the SSI cable.

The installation position was set within 300 mm of the host controller.

The shielded SSI cable should be connected to the ground of the converter's power terminal block.

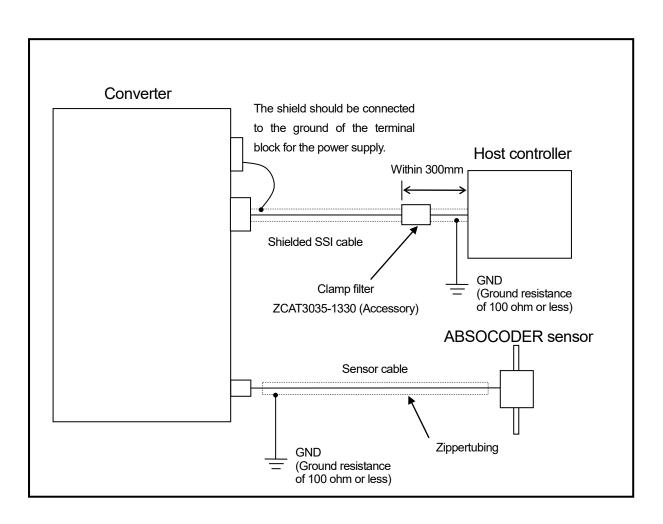
It close to the host controller should be connected to the ground.

#### Sensor cable

The sensor cable should be covered with the zippertubing with a shield, and the shield should be grounded close to the converter.

## Recommendation zippertubing

Model	Manufacturer
MTFS 20 $\phi$	ZIPPERTUBING (JAPAN), LTD.





## Manufacturer

NSD Corporation 3-31-28, OSU, NAKA-KU, NAGOYA, JAPAN 460-8302

# **Distributor**

NSD Trading Corporation 3-31-23, OSU, NAKA-KU, NAGOYA, JAPAN 460-8302

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